

Features on Demand

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Pierre-Yves Orban¹, Wolfgang De Meuter²

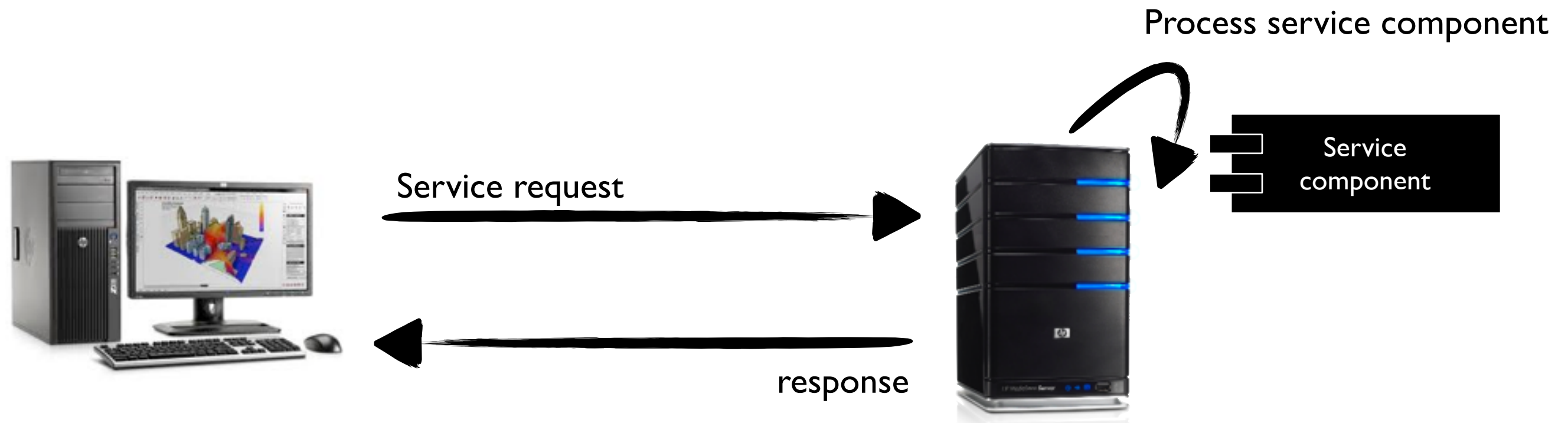
23 – 01 – 2014

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² Vrije Universiteit Brussel (ncardozo@vub.ac.be)

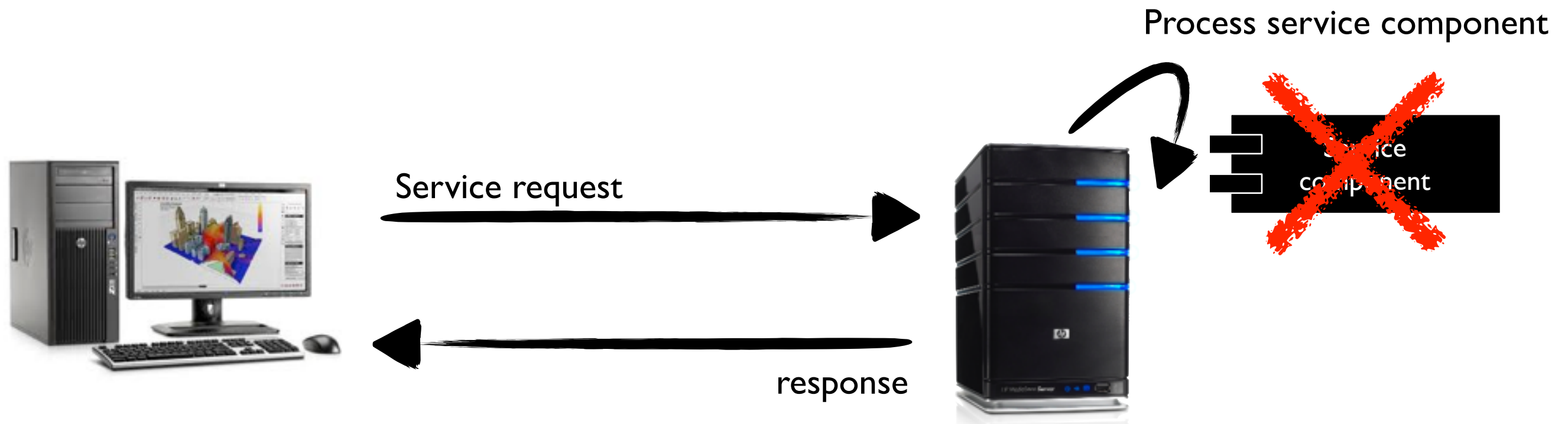
Service composition

2



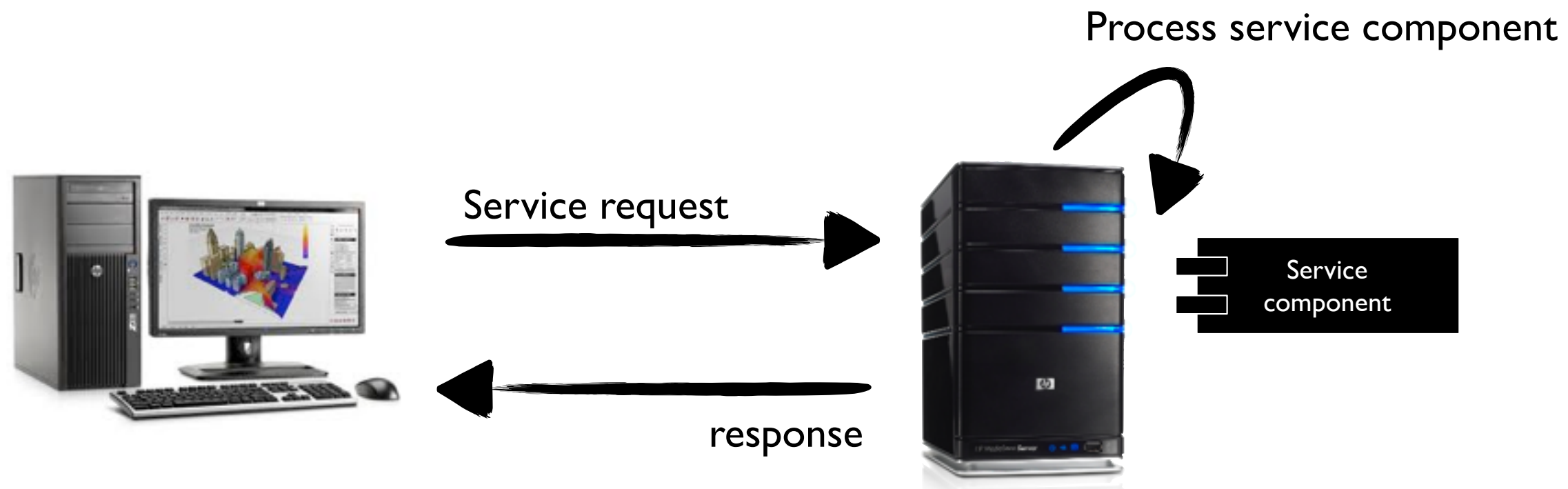
Service composition

2



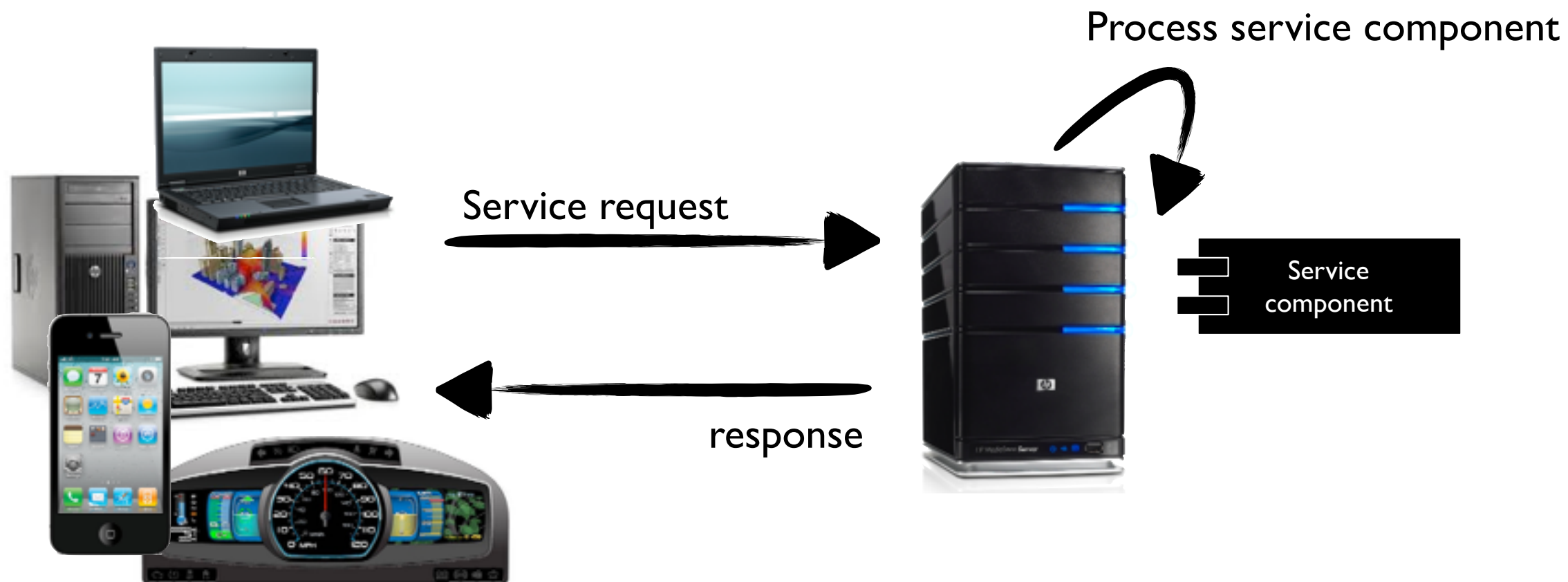
Feature clouds vision

3



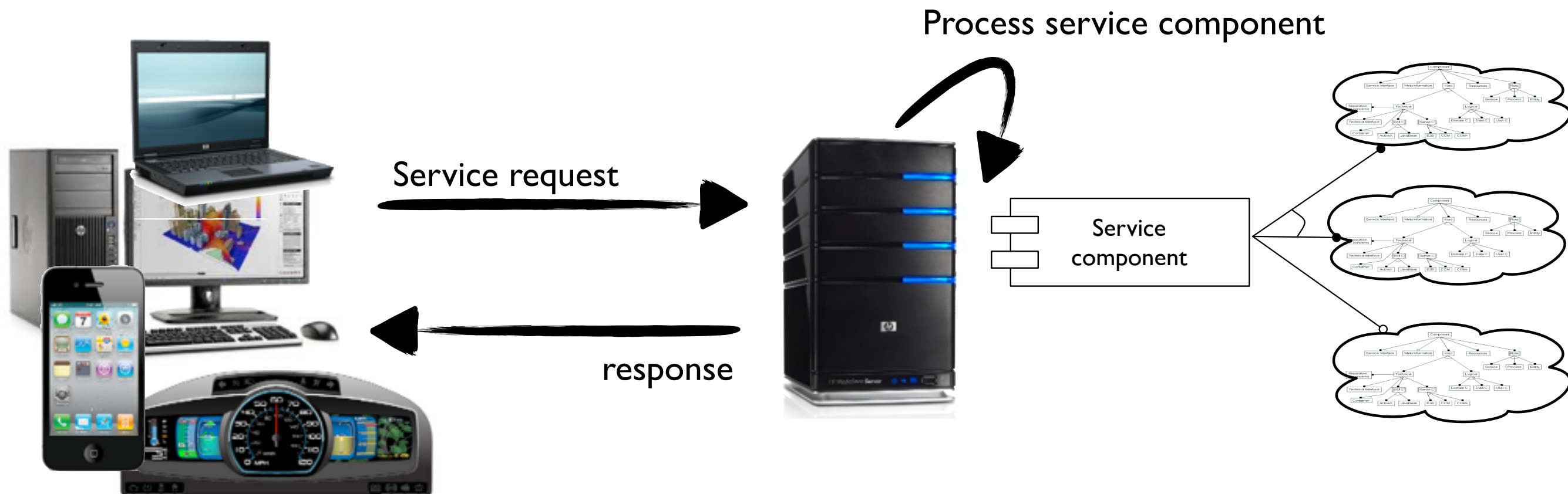
Feature clouds vision

3



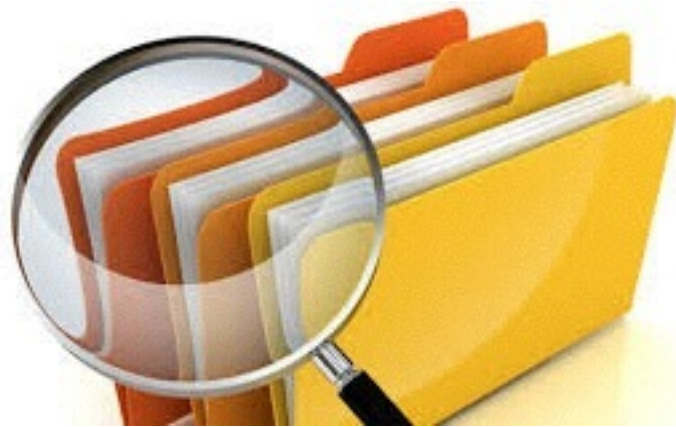
Feature clouds vision

3



Features on demand

4



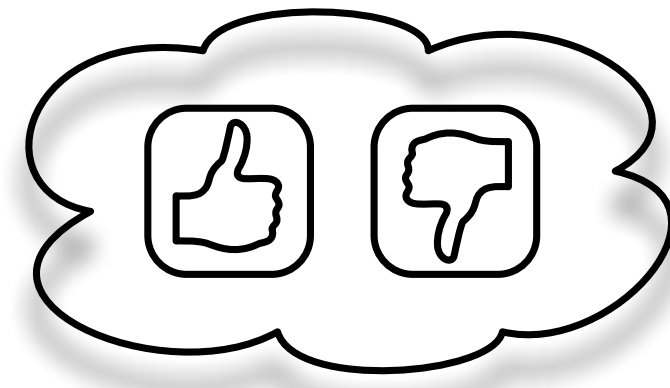
Motivating Example



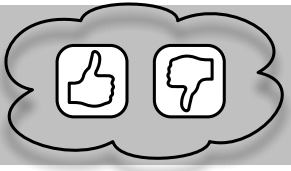
Requirements



Feature Clouds Model



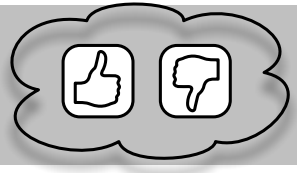
Conclusion



Motivating Example

On-board car system

6



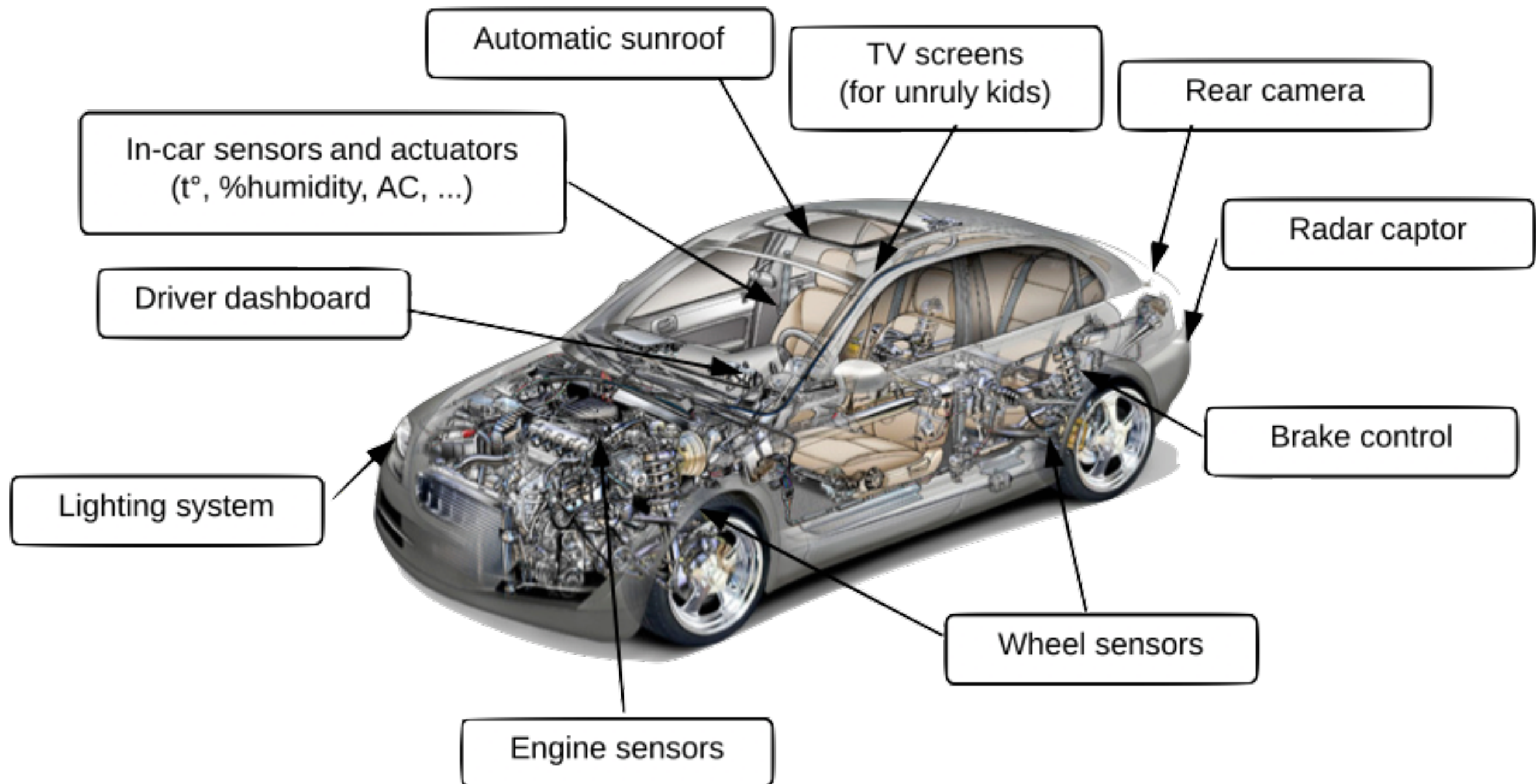
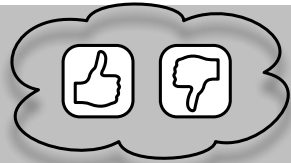
OBD Bluetooth adapter

Android device
(Samsung Galaxy Nexus i9250,
Android 4.3 Jelly Bean)



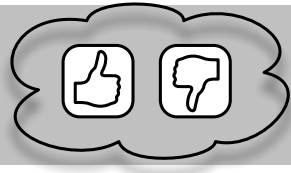
Feature clouds model

7



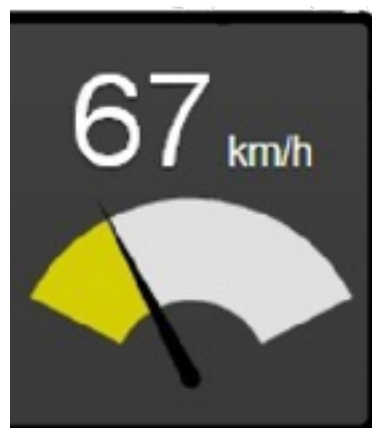
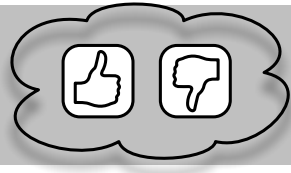
On-board car system

8



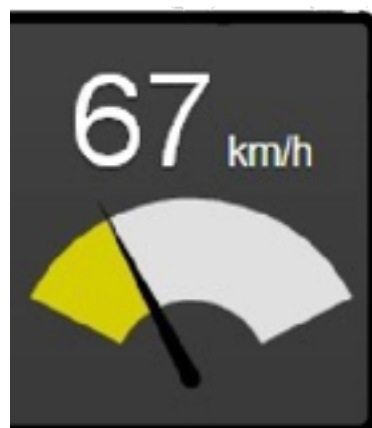
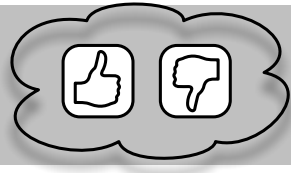
On-board car system

8



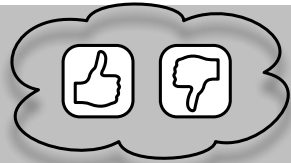
On-board car system

8












Feature store

9



Features Store

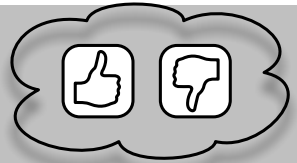
 RPM Gauge ★★★★★ Free	 Speed Gauge ★★★★★ Free	 Speed&RPM Gauge ★★★★★ Free
 Statistics ★★★★★ Free	 SMS Panel ★★★★★ Free	 SMS Sending ★★★★★ Free
 Notification Center	 SMS Notification	 Discreet SMS Notification

Back to the dashboard

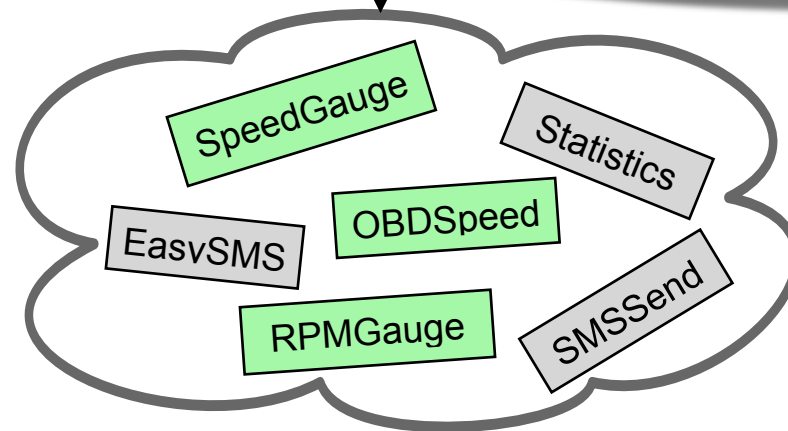


Feature interaction

10

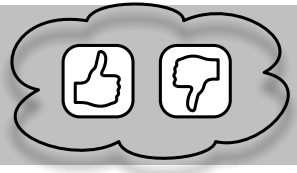


Assistent driving service request

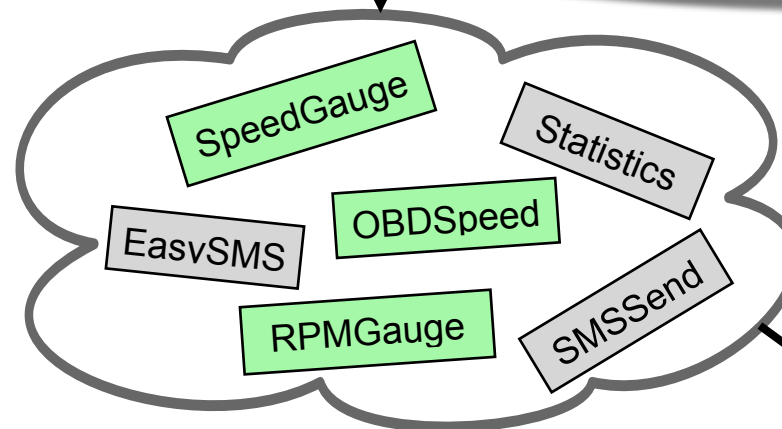


Feature interaction

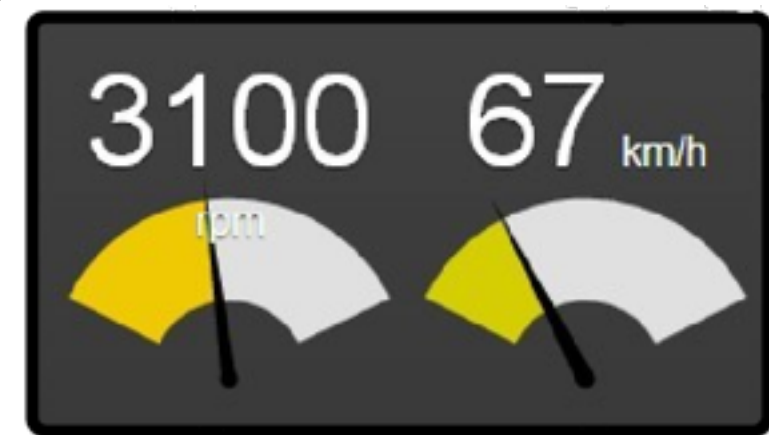
10



Assistent driving service request



no relation

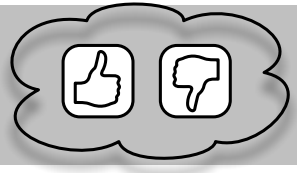


RPM Gauge

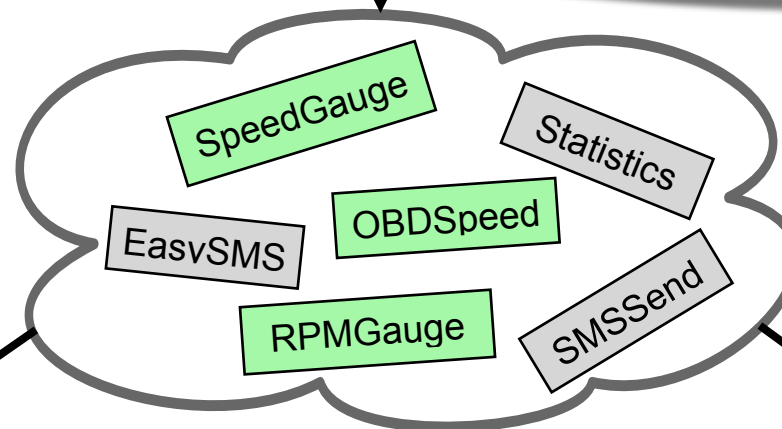
SpeedGauge

Feature interaction

10

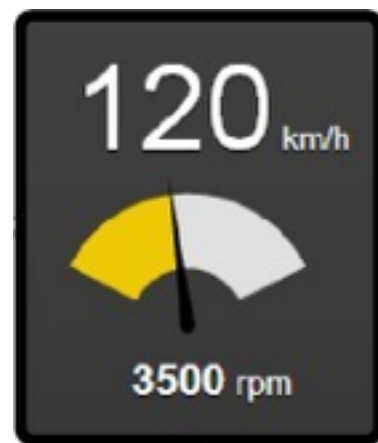


Assistent driving service request

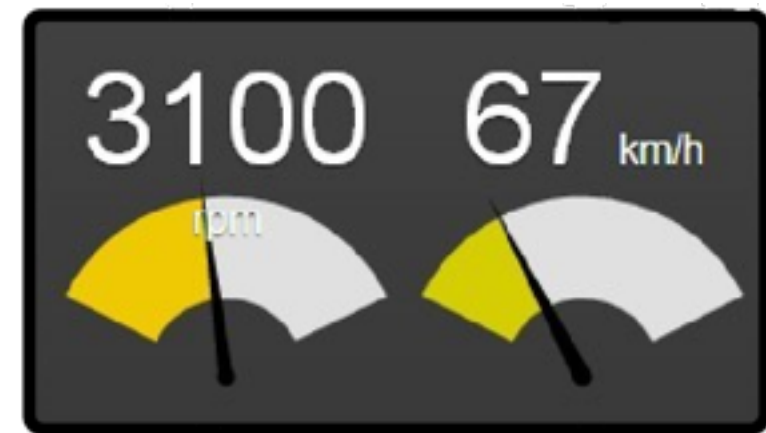


subsumption relation

no relation

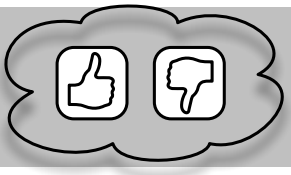


SpeedRPMGauge



RPM Gauge

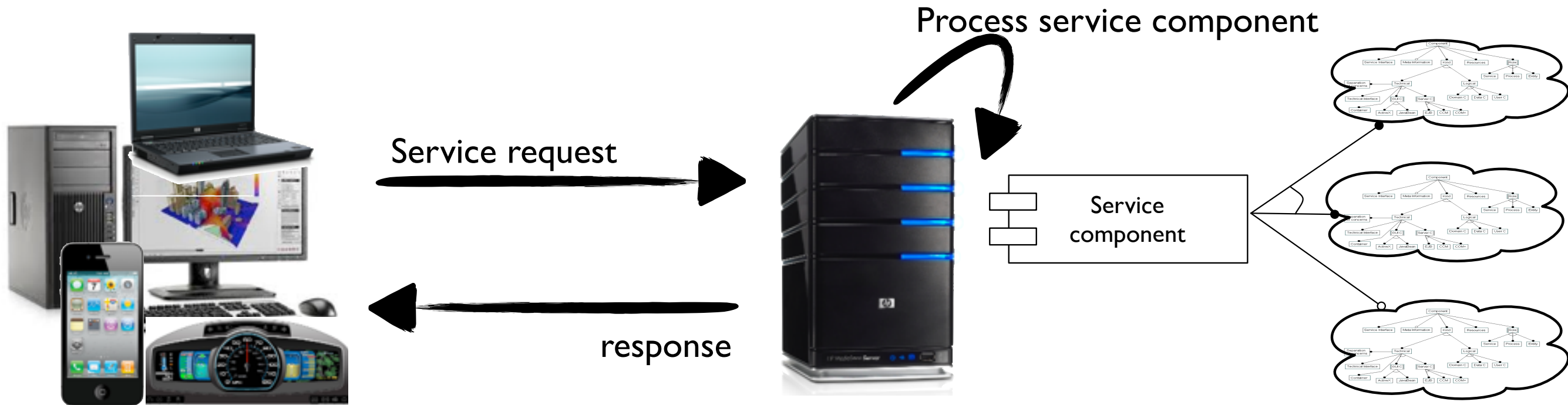
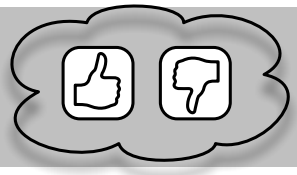
SpeedGauge



Requirements

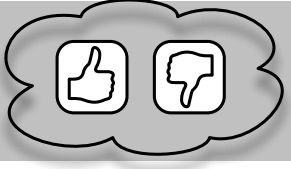
Feature clouds requirements

12



Feature clouds requirements

12



Dynamic behavior composition



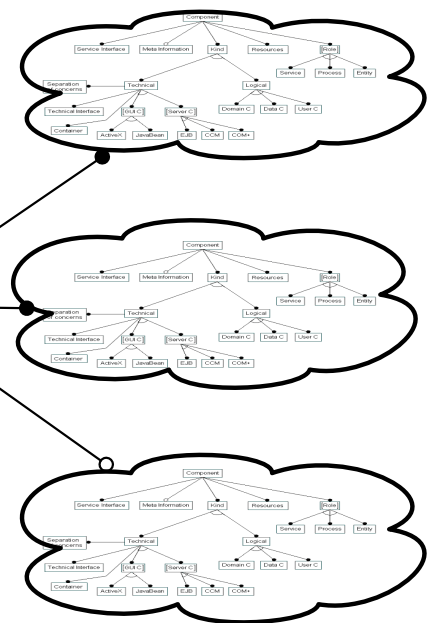
Service request



response

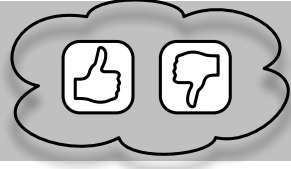


Process service component



Feature clouds requirements

12



Dynamic behavior composition

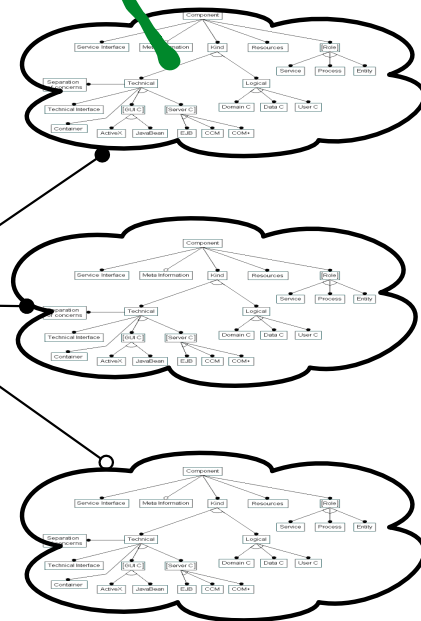
Fine-grained features

Process service component

Service request

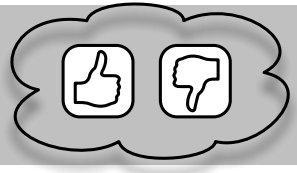
response

Service component



Feature clouds requirements

12



Dynamic behavior composition

Fine-grained features

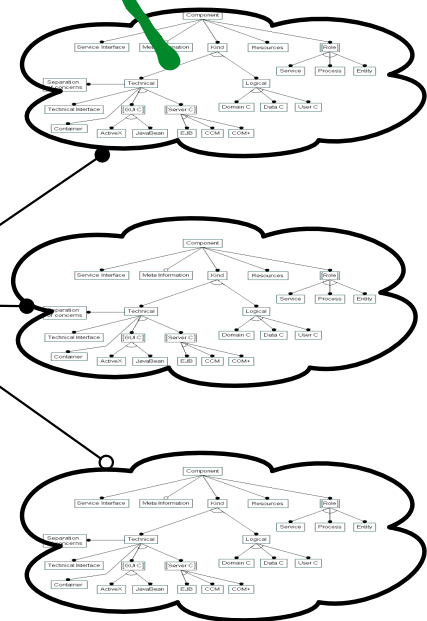
Process service component

Service request

Service component

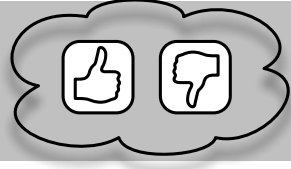
response

Manage feature interaction



Feature clouds requirements

12



Dynamic behavior composition

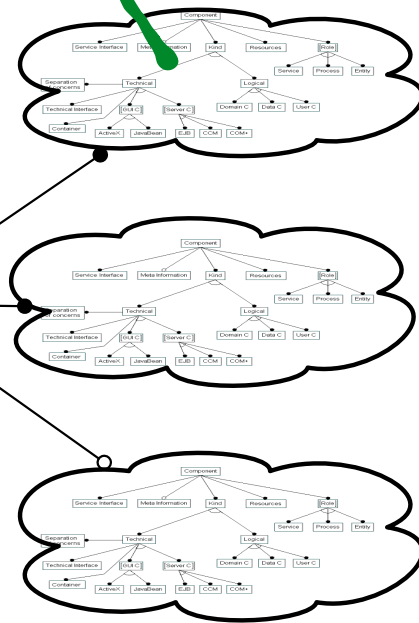
Fine-grained features

Process service component

Service request

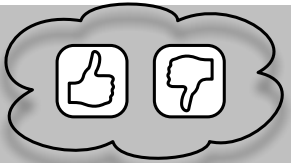
response

Service component



Manage feature interaction

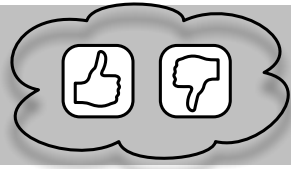
Appropriate infrastructure



Feature Clouds Model

Feature clouds model

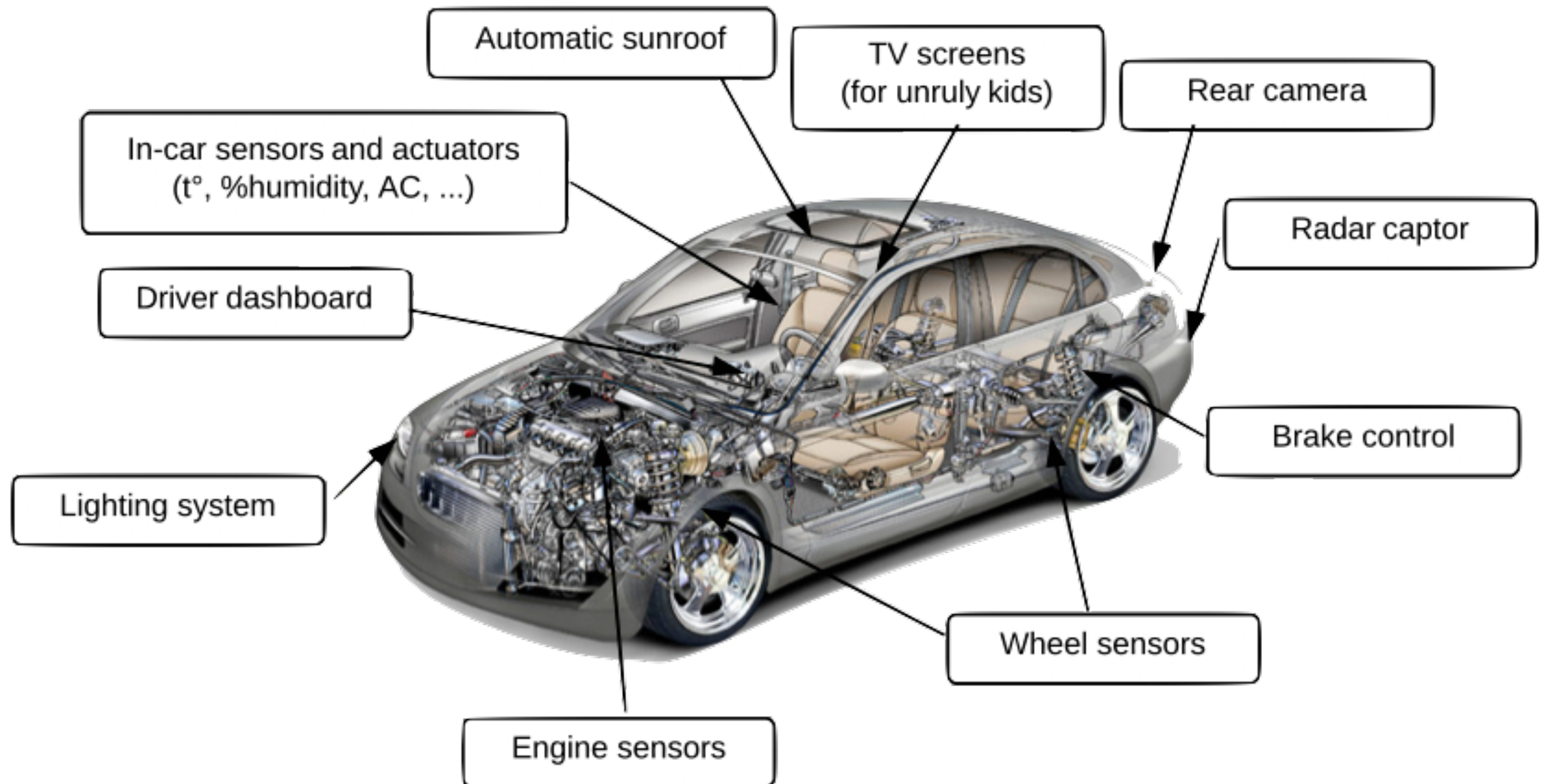
14



Feature-oriented programming

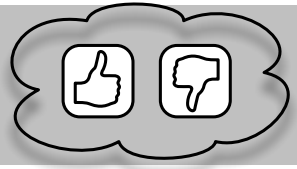
+

Context-oriented programming



Feature clouds model

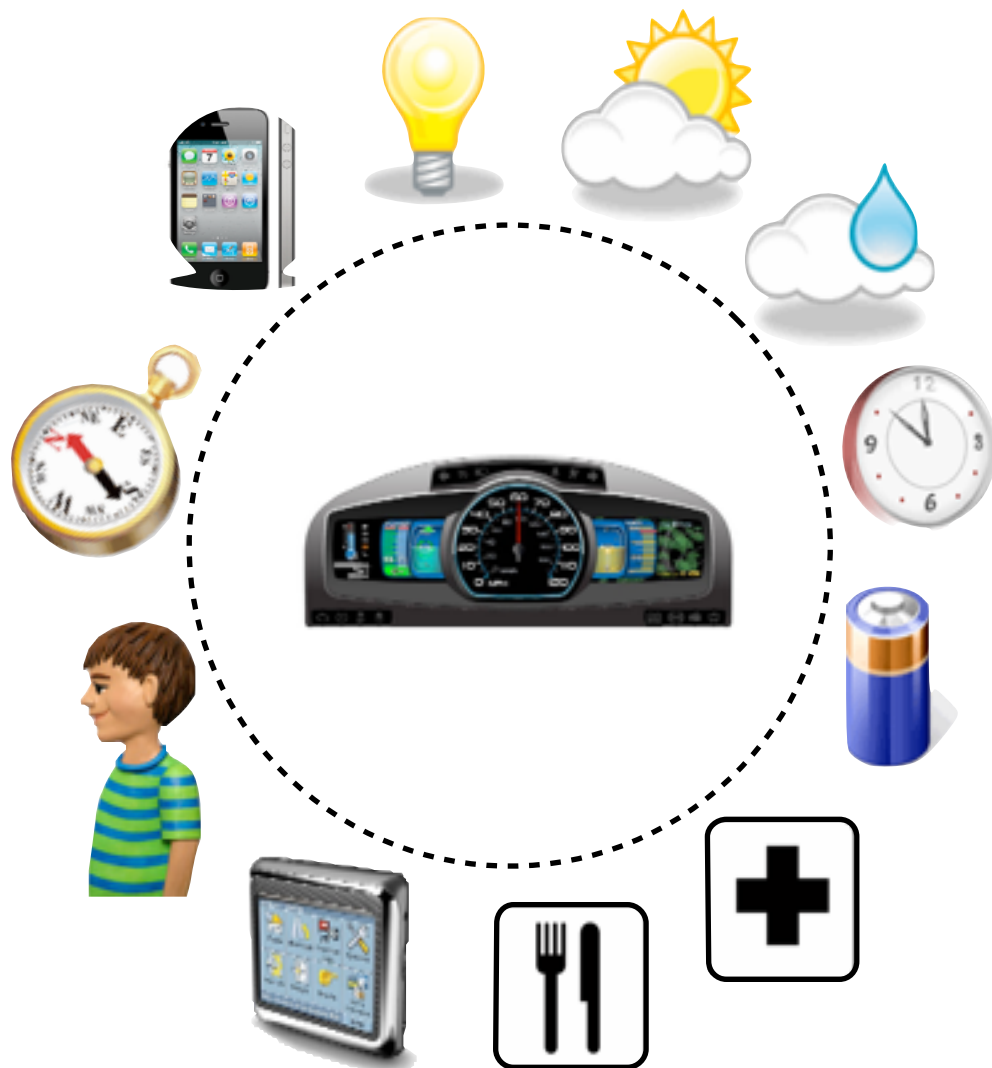
15



Feature-oriented programming

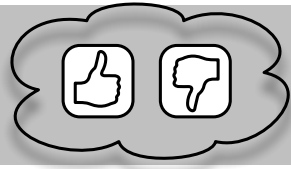
+

Context-oriented programming



Feature clouds model

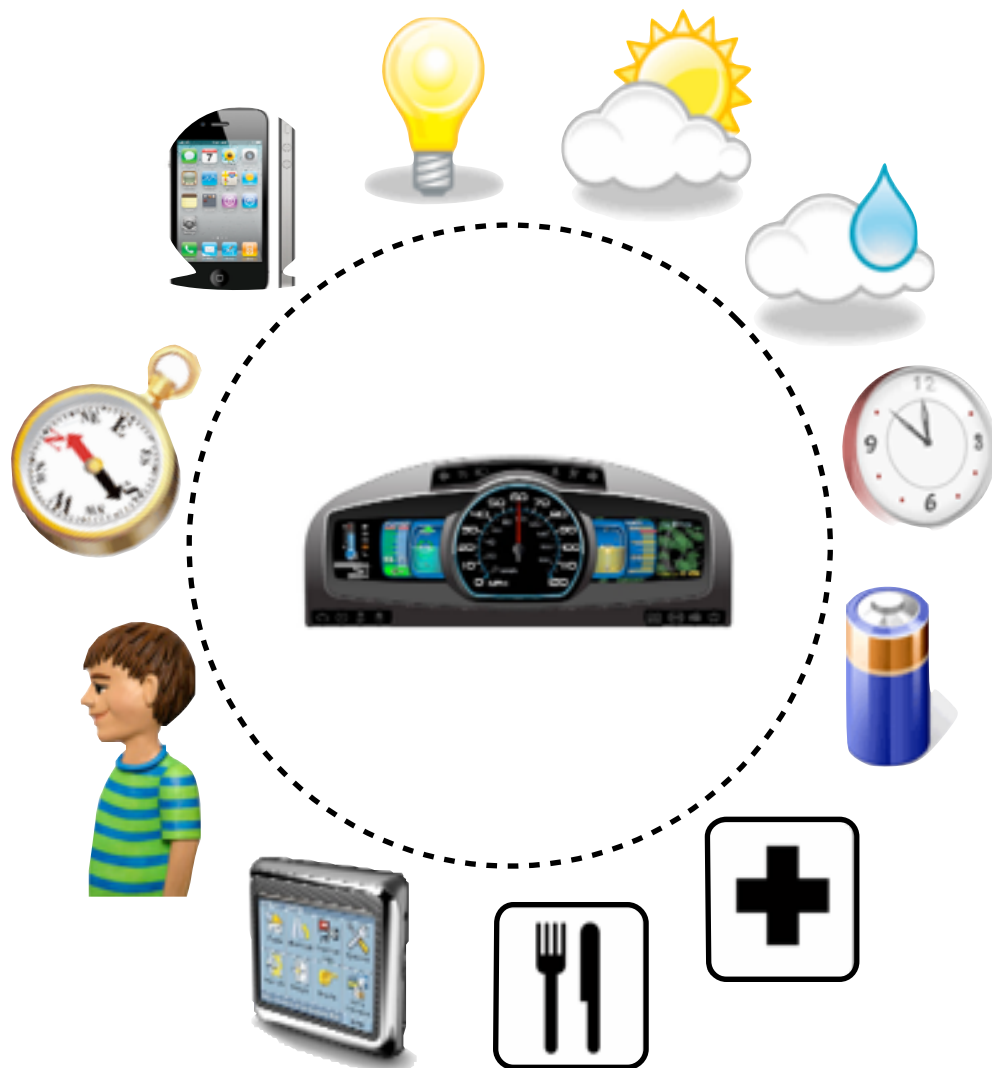
15



Feature-oriented programming

+

Context-oriented programming

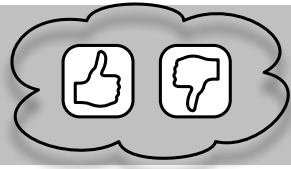


location = UK

Display speed reading
using the imperial system
units

Feature clouds model

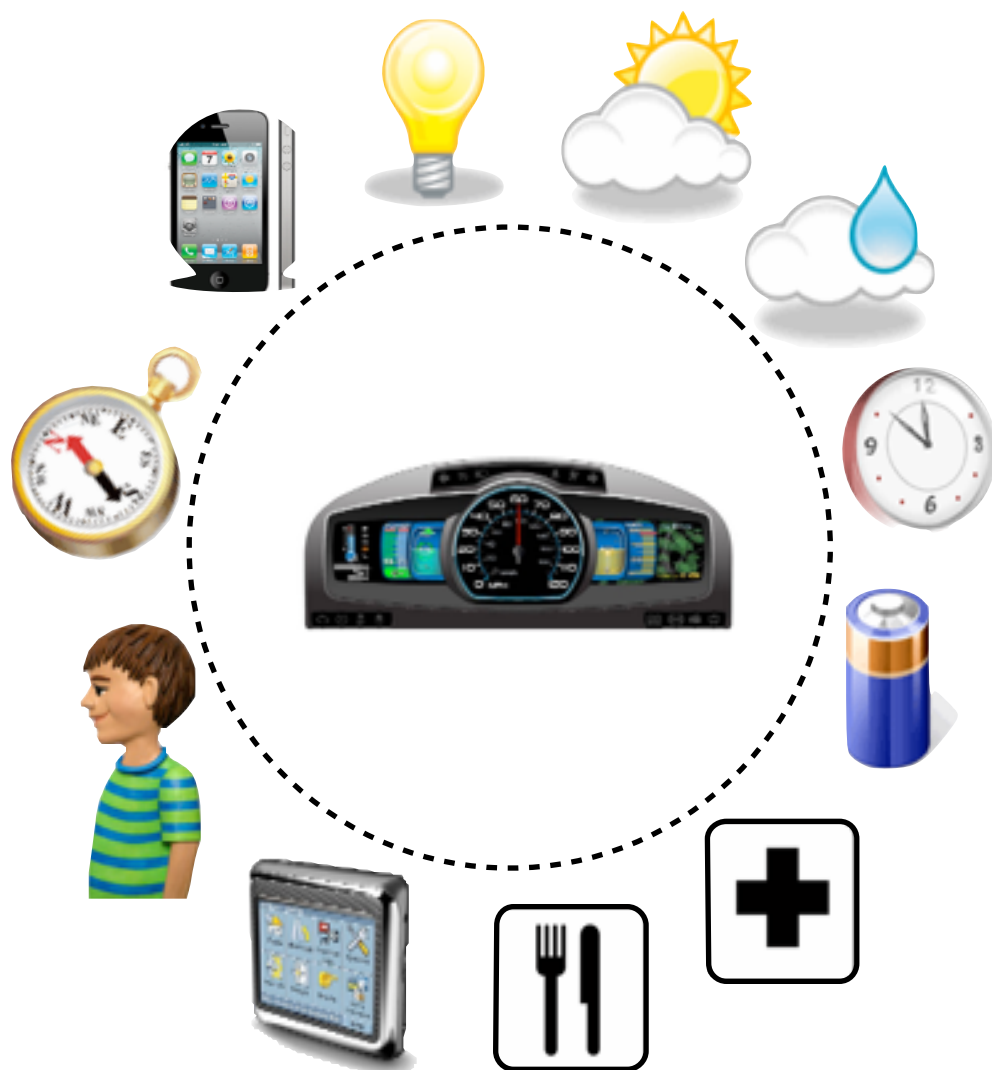
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Feature-oriented programming

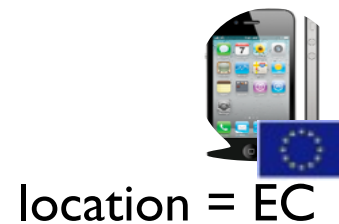
+

Context-oriented programming



location = UK

Display speed reading
using the imperial system
units

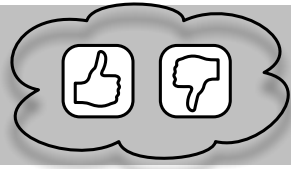


location = EC

Display speed reading
using the metric system
units

Feature clouds model

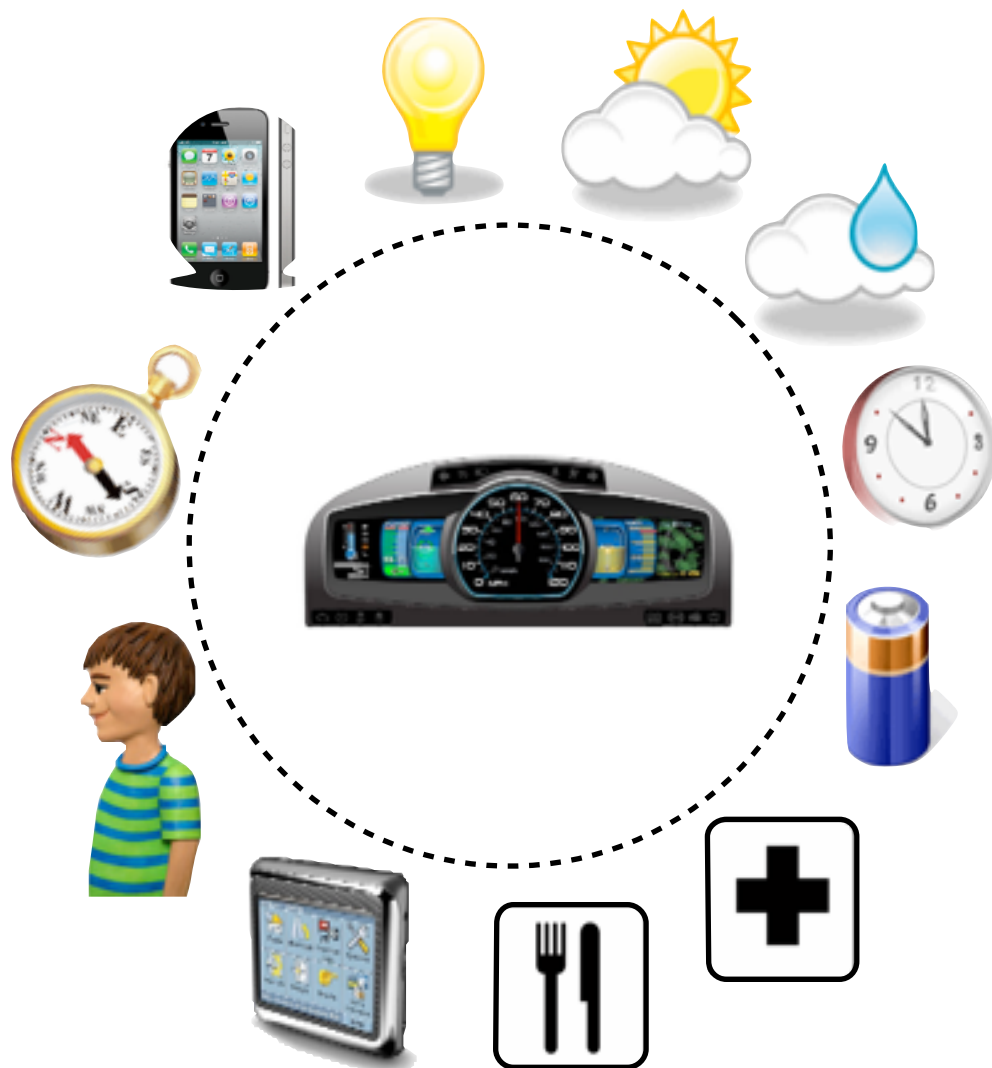
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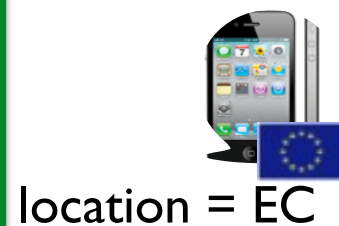
Feature-oriented programming

+

Context-oriented programming



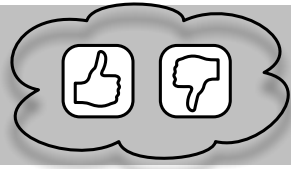
Display speed reading
using the imperial system
units



Display speed reading
using the metric system
units

Feature clouds model

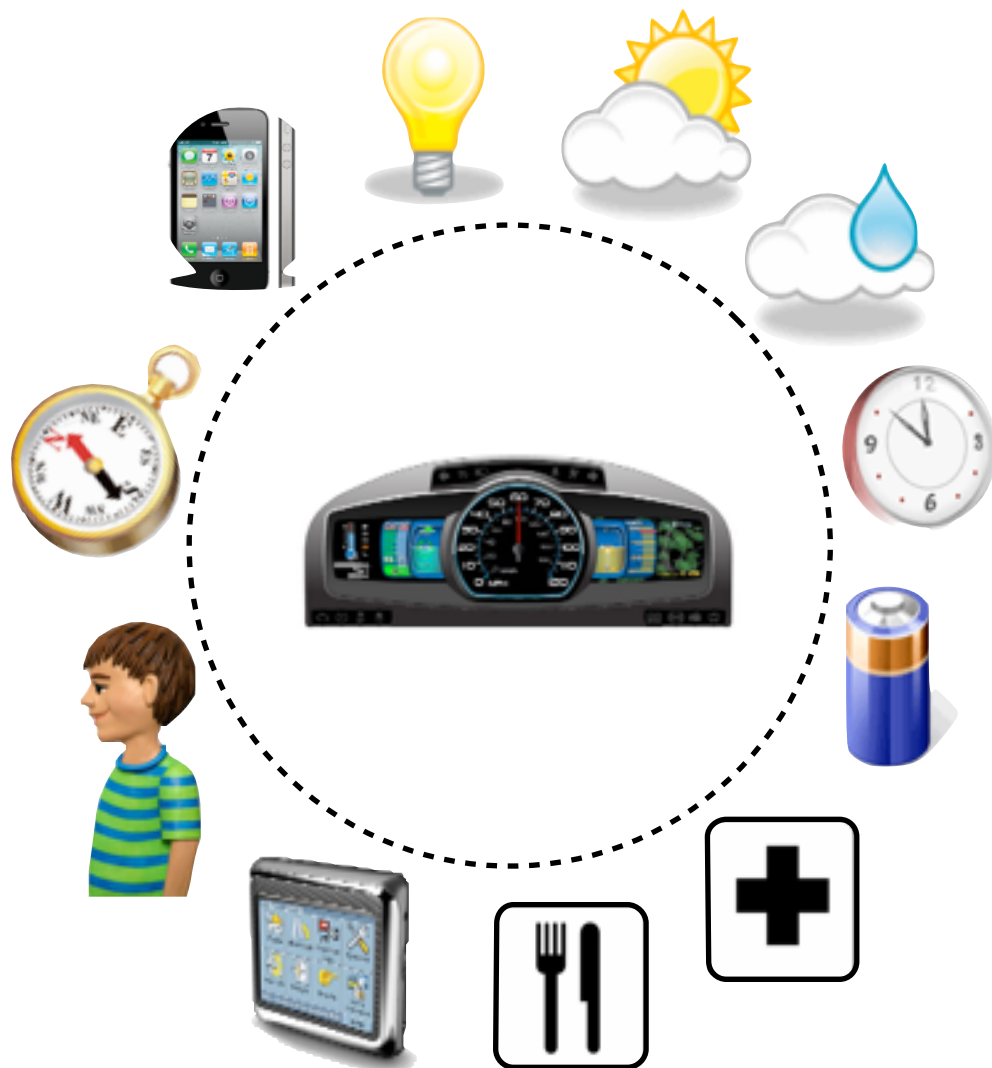
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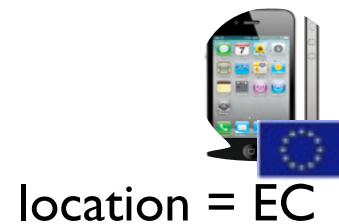
Feature-oriented programming

+

Context-oriented programming



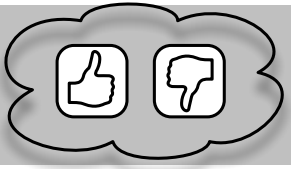
Display speed reading
using the imperial system
units



Display speed reading
using the metric system
units

Feature clouds model

16



contexts



```
UKSpeedGauge = new cop.Context ({  
    name: 'uk_speed_gauge' });
```

```
gps.EventListener('gps_reading',  
    function(location) {  
        if(location is 'UK')  
            UKSpeedGauge.activate();  
        else UKSpeedGauge.deactivate(); })
```

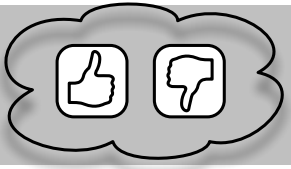
```
ImperialSystem = Trait{  
    var CONV_RATIO = 0.621371192;  
    getSpeed: function(msg) {  
        _val = this.proceed();  
        Math.round _val * CONV_RATIO; }  
  
    getHtml: function() {  
        display.setGaugeDisplay(this.proceed().replace("km/h", "mph")); }  
    };
```

```
UKSpeedGauge.adapt(SpeedGauge, ImperialSystem);
```

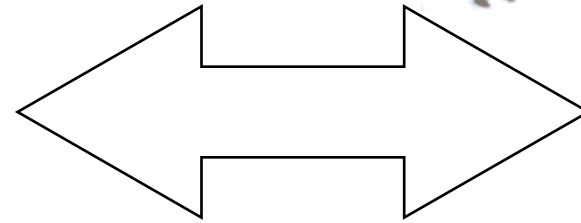


Feature clouds model

16



contexts



features



```
UKSpeedGauge = new Feature ({  
    name: 'uk_speed_gauge' });
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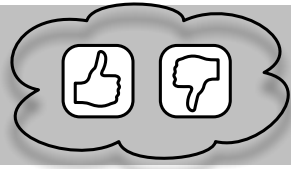
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        display.setGaugeDisplay(this.proceed().replace("km/h", "mph")); }  
    };
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UKSpeedGauge.adapt(SpeedGauge, ImperialSystem);
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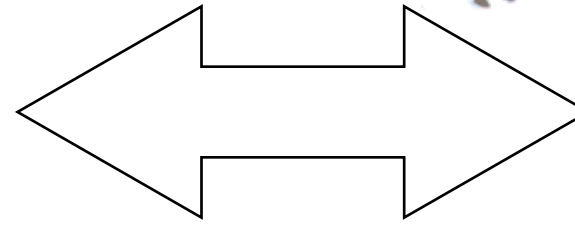


Feature clouds model

16



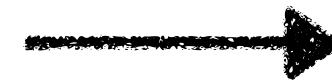
contexts



features



```
UKSpeedGauge = new Feature ({  
    name: 'uk_speed_gauge' });
```



Feature definition

```
gps.EventListener('gps_reading',  
    function(location) {  
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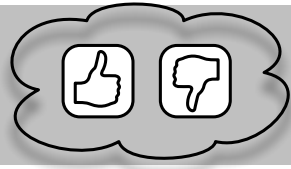
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    };
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UKSpeedGauge.adapt(SpeedGauge, ImperialSystem);
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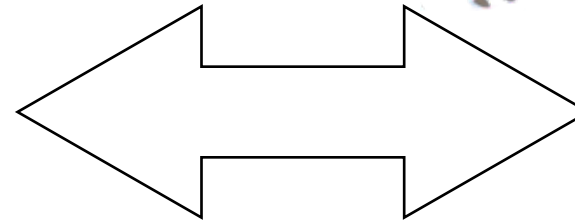


Feature clouds model

16



contexts



features

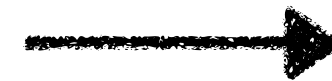


```
UKSpeedGauge = new Feature ({  
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```

```
gps.EventListener('gps_reading',  
    function(location) {  
        if(location is 'UK')  
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        else UKSpeedGauge.deactivate(); })
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ImperialSystem = Trait{  
    var CONV_RATIO = 0.621371192;  
    getSpeed: function(msg) {  
        _val = this.proceed();  
        Math.round _val * CONV_RATIO; }  
  
    getHtml: function() {  
        display.setGaugeDisplay(this.proceed().replace("km/h", "mph")); }  
    });
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UKSpeedGauge.adapt(SpeedGauge, ImperialSystem);
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Feature definition

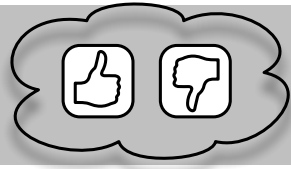


Feature selection

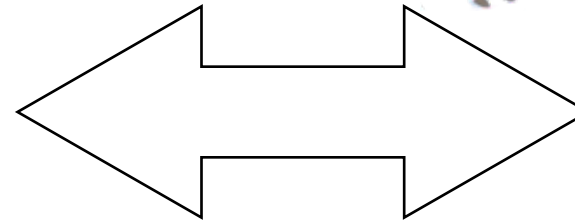


Feature clouds model

16



contexts



features

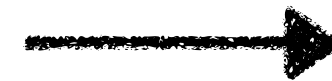


```
UKSpeedGauge = new Feature ({  
    name: 'uk_speed_gauge' });
```

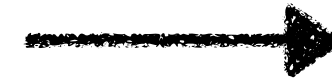
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    getSpeed: function(msg) {  
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        Math.round _val * CONV_RATIO; }  
  
    getHtml: function() {  
        display.setGaugeDisplay(this.proceed().replace("km/h", "mph")); }  
});
```

```
UKSpeedGauge.adapt(SpeedGauge, ImperialSystem);
```



Feature definition



Feature selection

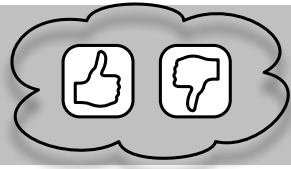


Behavior definition

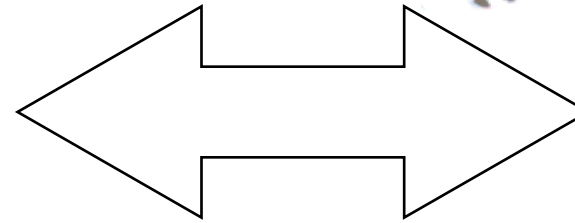


Feature clouds model

16



contexts



features

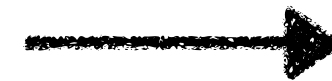


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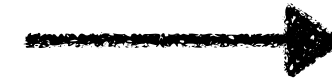
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        Math.round _val * CONV_RATIO; }  
  
    getHtml: function() {  
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});
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UKSpeedGauge.adapt(SpeedGauge, ImperialSystem);
```



Feature definition



Feature selection



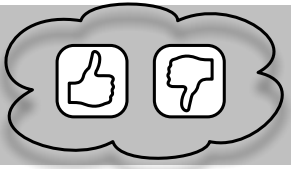
Behavior definition



Feature-behavior
association



17



Alternative

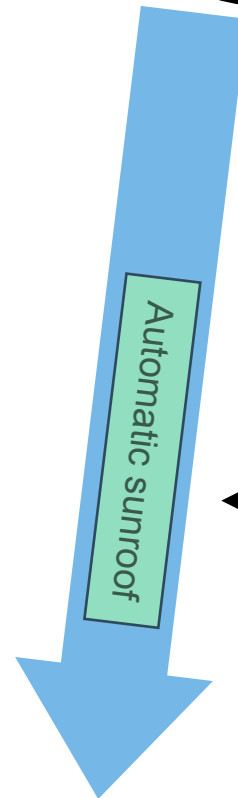
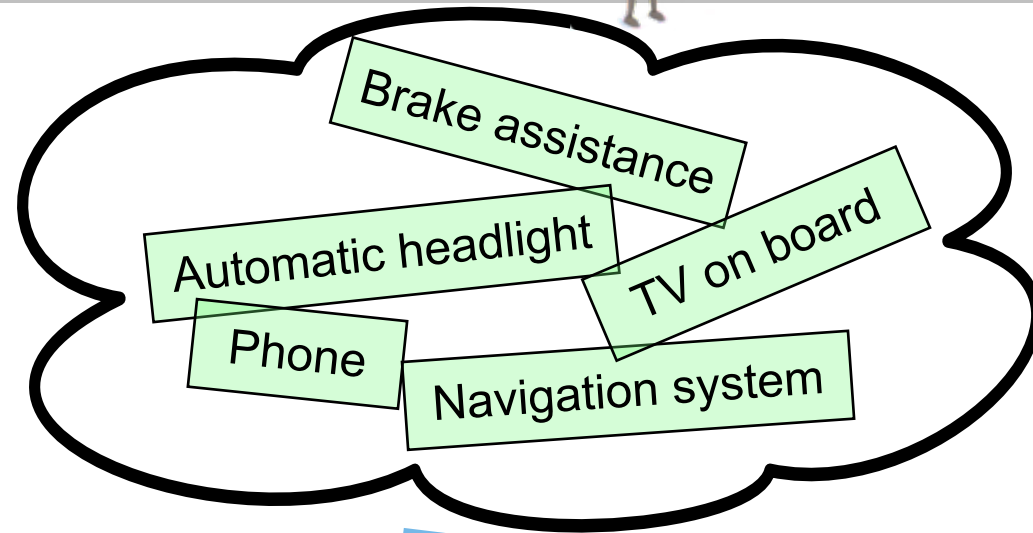
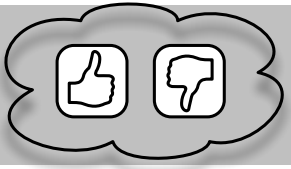
Specialize

Subsume

Combine

Feature clouds infrastructure

18



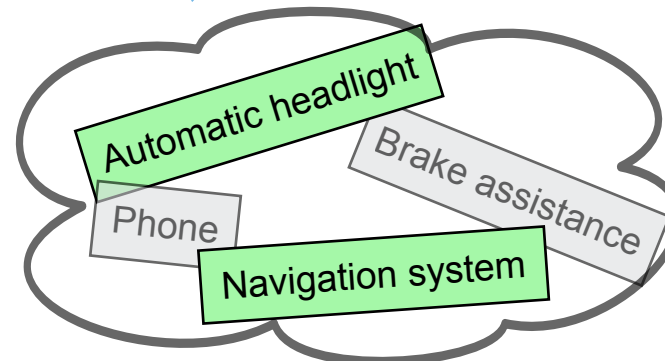
Features on Demand

Demand

Drop

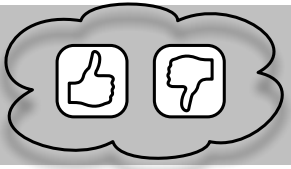


Heated seats

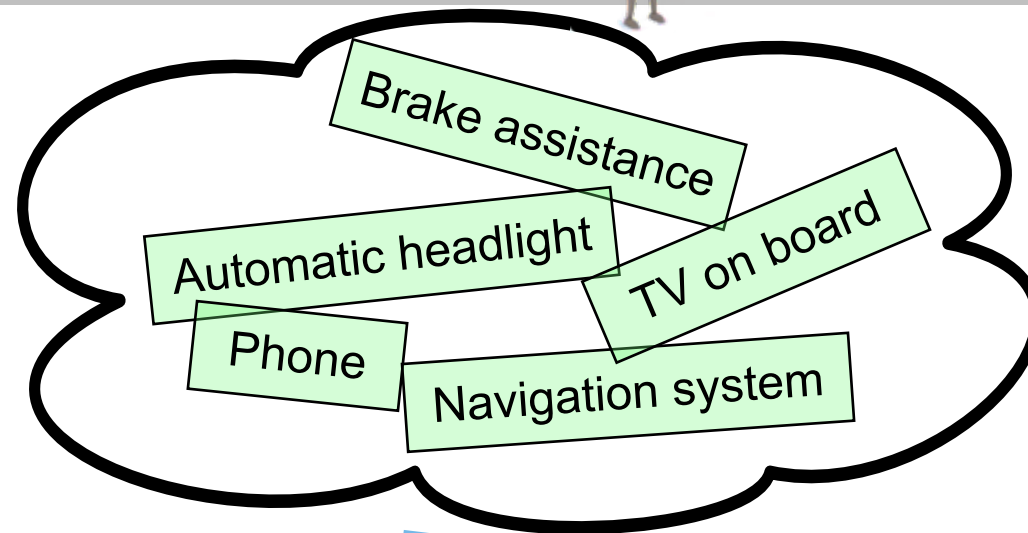


Feature clouds infrastructure

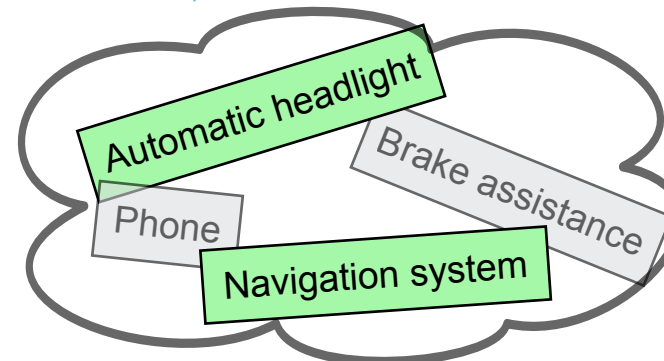
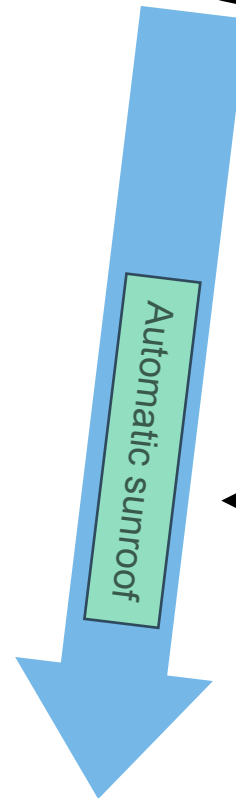
18



Feature Store



Features on Demand

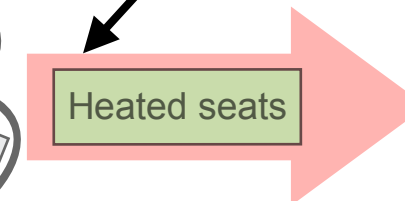


Demand



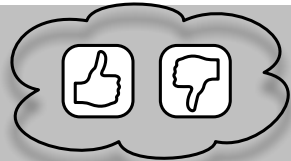
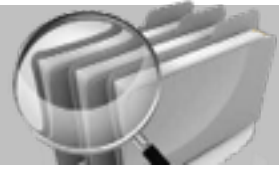
Drop

Heated seats

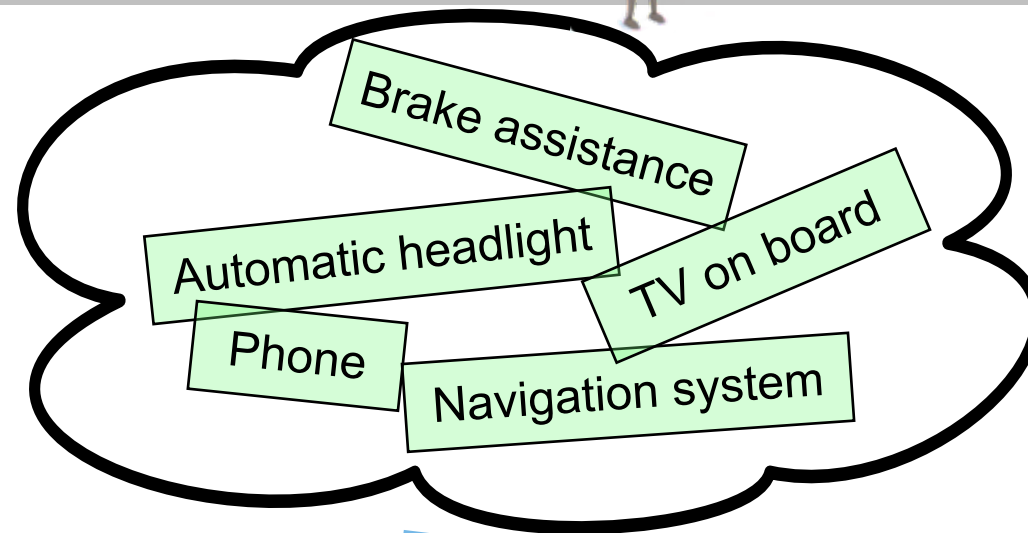


Feature clouds infrastructure

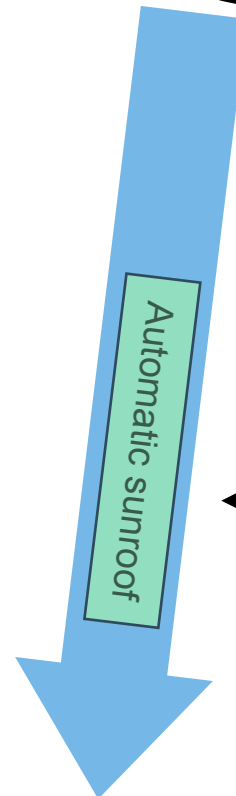
18



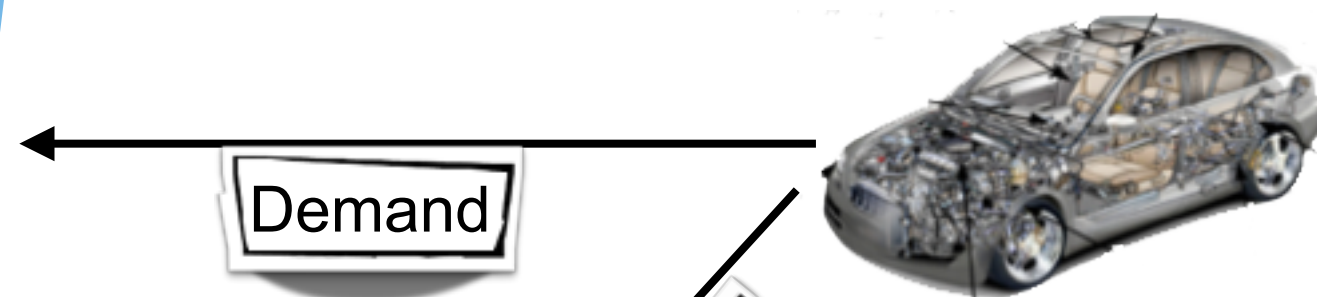
Feature Store



Features on Demand

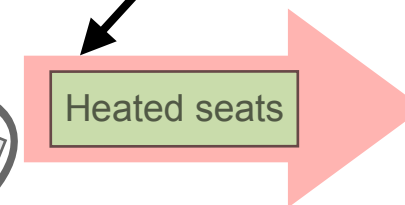
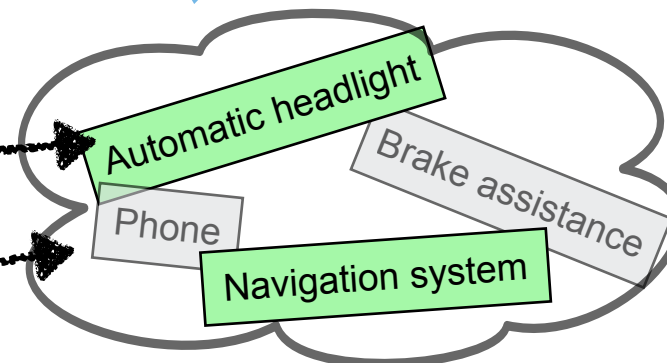


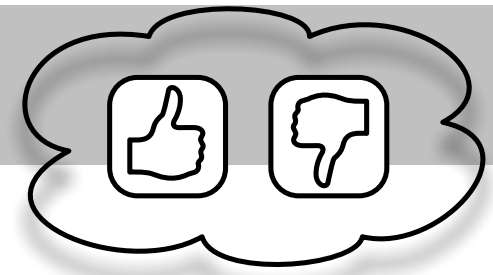
Feature Manager



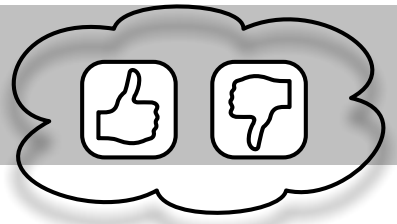
Active features

Inactive features





Conclusion



Feature Clouds

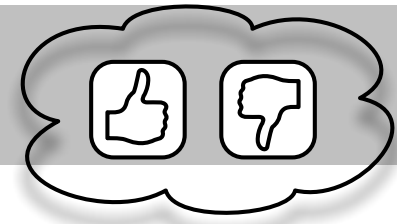
- ✓ Infrastructure for automated service composition

Feature Store

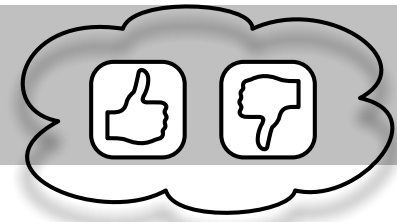
- ✓ Fine-grained feature definition

Feature Manager

- ✓ Dynamic selection and composition
- ✓ Feature interaction



- ❑ Granularity of features
 - ❑ does the approach remain manageable for a user or developer at this fine level of granularity?
- ❑ Third party features
- ❑ Run-time composition and verification
- ❑ Feature clouds infrastructure
 - ❑ need for a more holistic approach: in addition to behavioural aspect, also need to consider the data and UI aspects



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Questions?